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Equal-Budget Choice Equivalent Solutions in Exchange Economies*

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May 2006

Abstract

Given a family of linear budget sets, an allocation is *equal opportunity equivalent* (Thomson, 1994) if there exists a common budget set such that each agent is indifferent between the bundle that he gets and the best bundle he can obtain in the choice set. We first study the robustness properties of *equal opportunity equivalent* correspondences with respect to change in preferences. We impose *independence to irrelevant preference changes* and connect this property with the *implementation of rules via some game-theoretic solution concept*. We provide an equivalence result with the equal-income Walrasian rule. Next, we study robustness with respect to change in the number of agents and derive a characterization of the equal-income Walrasian rule. Our results provide additional justifications for the equal-division of resources as a first step toward fairness.

Keywords: Fair allocations, Equal-income Walrasian solution, Equal-budget choice equivalence, Robustness, Implementability via some game theoretical solution concept.

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1 Introduction

The literature on fair allocations is concerned with the division of several goods among agents with identical claims on the goods but different preferences. The model we use in this paper is that of exchange economies with a variable number N of agents and L infinitely divisible goods. An allocation rule that is central in this context is the *equal-income Walrasian rule*. Our position on *fairness* in this paper is that of *equality of choice* (Thomson, 1994). Given a family of choice sets, an allocation is *fair* if there exists a common choice set in that family such that each agent is indifferent between the bundle he is assigned and the best bundle he can obtain in the choice set.¹ This fairness property is termed *equal-opportunity equivalence*.² This notion generalizes many concepts used in the literature on fair allocations by appropriately choosing the family of choice sets \mathcal{B} . For instance, if $\mathcal{B} = \{x_0 : x_0 \in \mathbb{R}_+^L\}$, then the set of allocations that are *equal-opportunity equivalent with respect to \mathcal{B}* is the *egalitarian equivalent rule* introduced by Pazner and Schmeidler (1978). Next, if $\mathcal{B} = \{x : x \in \mathbb{R}_+^{Ln}\}$, the set of allocations that are *equal-opportunity equivalent with respect to \mathcal{B}* is the *envy-free rule* introduced by Foley (1968). Families of such choice sets may be of different dimensions and are indeed numerous.

We are interested in the family of linear choice sets. Given a common reference bundle α , a family of linear choice sets is parametrized by price vectors. An allocation rule is *equal-budget choice equivalent* with respect to a family of linear choice sets indexed by α if, for each preference profile, for each allocation x that the rule selects, there exists a price vector and a choice set such that each agent is indifferent between the bundle he gets at x and the best bundle he can afford in the common choice set.

Equal-budget choice equivalence combines idea of *egalitarian-equivalence* with that of *equal-opportunity* and *Walrasian equilibrium*. To fix ideas about the *equal-budget choice equivalent* allocation rules generated by such families, let α be the point of equal division of the aggregate endowment. Then, the *equal-budget choice equivalent* allocation rule generated is the *equal-income*

¹See also Nicolò and Perea (2005).

²In addition to the notion of *equal-opportunity equivalence*, Thomson (1994) first introduces the notion of *equal-opportunity*. The former obviously gives allocation rules that, in general, selects more allocations than the latter. Moreover, the former combines the idea of *equal-opportunities* with that of *egalitarian-equivalence*.

Walrasian rule.³ It has often been advocated that the point of equal division of resources is a first step towards equity and fairness. We wish to provide additional support to this claim.

We complement fairness with three robustness requirements, the first one with respect to changes in preferences and the other two with respect to changes in the number of agents when the feasible set is modified in an appropriate way. The former requirement is called *independence to irrelevant preference changes*. It simply states the invariance of an allocation rules with respect to change in preferences occurring only outside of the feasible set. It is a very weak property, weaker than Gevers monotonicity (see Gevers, 1986). Interestingly, this property has a clear link with the decentralization of allocation rules –i.e. their full implementation. After all, once rules satisfying desirable properties have been identified, the objective of a planner is to check whether there exist institutions–non-cooperative games–through which these allocation rules emerge as the equilibrium set of such games.

In fact, *independence to irrelevant preference changes* is a necessary condition for the *implementation of a rule via some game-theoretic solution concept*. We emphasize this connection and show that when preferences are continuous, monotonic and convex, then no allocation rule satisfies this requirement except when α belongs to the set of corners of the Edgeworth box. Thus, under this preference domain, the *equal-income Walrasian rule* is not implementable via any solution concept. However, by adding differentiability, it becomes implementable in subgame perfect equilibrium. We show that the only rule that satisfies *equal-budget choice equivalence*, *independence to irrelevant change in preferences* and *neutrality* is the *equal-income Walrasian rule*.

Next, the second robustness property we study is termed *consistency* (see Thomson, 1988). We show that the only rule that satisfies *equal-budget choice equivalence* and *consistency* is the *equal-income Walrasian rule*.

Finally, our last property is called *replication invariance* (see Thomson, 1988). We show that a *Pareto efficient* selection of an *equal-budget choice equivalent* rule satisfies *consistency* and *replication invariance* if and only if it is a subrule of the *equal-income Walrasian rule*. This result is in line with Theorem 3 in Thomson (1988).

The paper proceeds as follows. In section two, we introduce the necessary definitions and notations. Section three presents the main results and offers

³See Proposition 1 in section 3 for a formal proof of this statement.

some concluding remarks.

2 Definitions and notations

There are L infinitely divisible goods, $L \geq 2$, and a finite set of agents $N = \{1, 2, \dots, n\}$ drawn from an infinite population \mathcal{N} , with $n \geq 2$. The consumption set of each agent $i \in N$ is \mathbb{R}_+^L . For each agent $i \in N$, R_i is the complete and transitive binary relation on \mathbb{R}_+^L indicating (weak) preferences. The associated strict preference and indifference relations are denoted by P_i and I_i , respectively. The set of possible preferences of each agent $i \in N$ is defined by \mathcal{R}_i . Denote by $\mathcal{R}^N = \prod_{i \in N} \mathcal{R}_i$ the set of possible preference profiles. A typical preference profile is $R = (R_i)_{i \in N} \in \mathcal{R}^N$. For each $R \in \mathcal{R}^N$ and each $M \subset N$, let $R_M = (R_i)_{i \in M}$.

We take as given the aggregate endowment $\bar{\omega} \gg 0$.⁴ Once the set of agents is fixed, $\bar{\omega}$ is also fixed across preference profiles. An economy is thus simply a list of preference relations and an aggregate endowment. Formally, given N , an economy is a list $(R, \bar{\omega}) \in E = \{\mathcal{R}^N \times \mathbb{R}_+^L: n \in \mathbb{N}\}$. We consider two classes of preferences that define two domains of economies E_C^N and E_D^N .⁵

Class of preferences \mathcal{R}_C^N : For each agent $i \in N$, each $R_i \in \mathcal{R}_i$ is continuous, convex and monotonic.⁶

Class of preferences \mathcal{R}_D^N : For each agent $i \in N$, each $R_i \in \mathcal{R}_i$ is convex, monotonic and representable by a differentiable utility function.

Given an aggregate endowment $\bar{\omega}$, a (feasible) allocation is a list of bundle $(x_i)_{i \in N} \in \mathbb{R}_+^{Ln}$ such that $\sum x_i \leq \bar{\omega}$. Given an agent $i \in N$, $x_i^l \in \mathbb{R}_+$ stands for the quantity of good l received by agent i at bundle x_i . For any allocation x , and any $M \subset N$, let x_M stand for the sub-allocation restricted to agents in M . Likewise, let $x_{N \setminus M}$ stand for the sub-allocation restricted to agents in $N \setminus M$.

⁴We order vectors with the usual conventions, $\gg, >, \geq$.

⁵ R_C^N is the domain of classical preferences, while for R_D^N is the subdomain of classical preferences that are representable by a differentiable utility function.

⁶A preference relation R_i defined over \mathbb{R}_+^L is convex if, for every x_i and $y_i \in \mathbb{R}_+^L$ such that $x_i P_i y_i$, we have that $\lambda x_i + (1 - \lambda)y_i P_i y_i$ for every $\lambda \in (0, 1]$.

A preference relation R_i defined over \mathbb{R}_+^L is monotonic if, for each x_i and $y_i \in \mathbb{R}_+^L$, $x_i \gg y_i$ implies that $x_i P_i y_i$.

Given $\bar{\omega}$, the set of feasible allocations $A(\bar{\omega})$ is,

$$A(\bar{\omega}) = \{x \in \mathbb{R}_+^{Ln} : \sum x_i \leq \bar{\omega}\}.$$

Let A_i be the projection of A onto agent i 's consumption space. Formally,

$$A_i(\bar{\omega}) = \{x_i \in \mathbb{R}_+^L : x_i^\ell \in [0, \bar{\omega}^\ell] \text{ for each } \ell = 1, \dots, L\}.$$

A bundle x_i is a non-trivial corner of $A_i(\bar{\omega})$ if $x_i^\ell = \bar{\omega}^\ell$ and $x_i^k = 0$ for some $\ell, k \leq L$. We say that x_i is a trivial corner of A_i if $x_i^\ell = \bar{\omega}^\ell$ for each $\ell = 1, \dots, L$ or $x_i^\ell = 0$ for each $\ell = 1, \dots, L$.

An allocation $x \in A(\bar{\omega})$ is a non-trivial corner of $A(\bar{\omega})$ —the Edgeworth cube— if there exists $i \in N$ such that x_i is a non-trivial corner of $A_i(\bar{\omega})$. Trivial corners of $A(\bar{\omega})$ are defined in the same fashion. Let $C(A(\bar{\omega}))$ be the set of non-trivial corners of the Edgeworth cube. Abusing language, we say that a bundle x_i is an element of $C(A(\bar{\omega}))$ if it is a non-trivial corner of $A_i(\bar{\omega})$. From now on, we refer to non-trivial corners simply as corners. This should cause no confusion.

Let Δ^{L-1} be the $(L-1)$ -dimensional simplex. For each agent $i \in N$, denote by $B_i(p, \alpha)$ the budget set generated by $p \in \Delta^{L-1}$ and the bundle $\alpha \in A_i$.

$$B_i(p, \alpha) \equiv \{x_i \in A_i(\bar{\omega}) : p \cdot x_i \leq p \cdot \alpha\}.$$

Given an agent $i \in N$, a preference relation $R_i \in \mathcal{R}_i$ and a bundle $x_i \in A_i(\bar{\omega})$, define $LC_i(x_i, R_i) = \{y_i \in A_i(\bar{\omega}) : x_i R_i y_i\}$ to be the lower contour set at x_i ; $UC_i(x_i, R_i) = \{y_i \in A_i(\bar{\omega}) : y_i R_i x_i\}$ the upper contour set at x_i ; $SLC_i(x_i, R_i) = \{y_i \in A_i(\bar{\omega}) : x_i P_i y_i\}$ the strict lower contour set at x_i and $I_i(x_i, R_i) = \{y_i \in A_i(\bar{\omega}) : x_i I_i y_i\}$, the indifference curve through x_i .

We are interested in allocation rules satisfying several desirable properties. An allocation rule $f : E \rightarrow A(\bar{\omega})$ is a correspondence that associates to each preference profile a set of allocations. Let $\arg \max R_i|_{B_i(p, \alpha)}$ be the set of maximizers of the preference relation R_i over the set $B_i(p, \alpha)$.

Definition: The allocation $x \in A(\bar{\omega})$ is an *equal-income Walrasian allocation* for $(R, \bar{\omega}) \in E^N$ if there exists $p \in \Delta^{L-1}$ such that for all $i \in N$, $x_i \in \arg \max R_i|_{B_i(p, \frac{\bar{\omega}}{n})}$.

The *equal-income Walrasian correspondence* $WE_E : E^N \rightarrow A(\bar{\omega})$ associates to each economy $(R, \bar{\omega})$ its set of *equal-income Walrasian allocations*.

Definition: Given $(R, \bar{\omega}) \in E^N$, the allocation $x \in A(\bar{\omega})$ is *Pareto efficient* if there does not exist $y \in A(\bar{\omega})$ such that $y_i \succ R_i x_i$ for each $i \in N$ and $y_j \succsim P_j x_j$ for some $j \in N$.

Given $(R, \bar{\omega}) \in E^N$, an allocation $x \in A(\bar{\omega})$ is derived from a choice set $B \subset \mathbb{R}_+^L$ if for each $i \in N$ we have that $x_i \in B$. Define by \mathcal{B} a family of choice sets.

Definition: An allocation $x \in A(\bar{\omega})$ is *equal-opportunity equivalent relative to the family \mathcal{B}* for $(R, \bar{\omega}) \in E^N$ if there exists $B \in \mathcal{B}$ such that for each $i \in N$, $x_i \succsim I_i x_i^*$ for each $x_i^* \in \arg \max R_i|_B$.

The family of choice sets we gave is very large. We will restrict our attention to families of linear choice sets. A family of linear choice sets is indexed by a bundle $\alpha = \alpha_{\bar{\omega}} \cdot \bar{\omega} = (\alpha_{\bar{\omega}_1} \cdot \bar{\omega}_1, \dots, \alpha_{\bar{\omega}_L} \cdot \bar{\omega}_L)$, with $\alpha_{\bar{\omega}_\ell} \in [1, 0]$ for each $\ell = 1, \dots, L$, and parametrized by price vectors $p \in \Delta^{L-1}$.⁷ That is, once a point $\alpha \in \mathbb{R}_+^L$ has been fixed, the family of choice sets contains every budget set generated by $p \in \Delta^{L-1}$ and α . More formally, given $\alpha \in \mathbb{R}_+^L$ and $p \in \Delta^{L-1}$, let $B_\alpha(p) \equiv \{z \in \mathbb{R}_+^L : p \cdot z \leq p \cdot \alpha\}$ and $\mathcal{B}_\alpha \equiv \{B_\alpha(p) : p \in \Delta^{L-1}\}$.

We are interested in several properties of allocation rules. Our first requirement is an axiom of fairness.

Equal-budget choice equivalence: A solution f satisfies *equal-budget choice equivalence relative to \mathcal{B}_α* if,

1) For each $(R, \bar{\omega}) \in E^N$, each $x \in f(R, \bar{\omega})$ is *equal-opportunity equivalent* relative to the family \mathcal{B}_α for $(R, \bar{\omega})$.

2) There does not exist an *equal-opportunity equivalent allocation y relative to \mathcal{B}_α* for $(R, \bar{\omega})$ such that $y \notin f(R, \bar{\omega})$.

Given α , let f_α be the *equal-budget choice equivalent* allocation rule relative to \mathcal{B}_α . Our next property requires a form of robustness with respect to change in preferences. It states the invariance of a rule to changes in preferences occurring only outside of the feasible set of allocations.

Independence to irrelevant preference changes: A solution f satisfies *independence to irrelevant preference changes* if and only if for each

⁷The reference point can be written as α or $\alpha_{\bar{\omega}} \cdot \bar{\omega}$. For convenience, we use both notations in the paper but it should not cause confusion.

$(R, \bar{\omega}), (R', \bar{\omega}) \in E^N$ and $x \in f(R, \bar{\omega})$,

$[R \neq R' \text{ and } R_i \cap A_i(\bar{\omega}) = R'_i \cap A_i(\bar{\omega}) \text{ for each } i \in N] \implies [x \in f(R', \bar{\omega})]$.

Our third property states the robustness of a rule with respect to changes in the number of agents when the feasible set is modified in an appropriate way. We define the property directly with respect to rules f_α : when a group of agents leaves the economy, not only they modify the feasible set of allocations, but they also modify the initial reference point α .

Consistency: An allocation rule f_α satisfies *consistency* if and only if for each $(R, \bar{\omega}) \in E^N$, each $x \in f(R, \bar{\omega})$, each $M \subset N$,

$$x_{N \setminus M} \in f_{\alpha_{\bar{\omega}} \cdot x_{N \setminus M}}(R \setminus R_M, \sum_{i \in N \setminus M} x_i).$$

Consistency pertains to a decreasing number of agents. An allocation rule is *consistent* if and only if any sub-allocation of a selected allocation is also selected in the “reduced” economy defined by the corresponding subset of agents and the set of allocations which can be considered as feasible for this subset of agents. An allocation is feasible for a subset of agents if it is possible to reach it while guaranteeing the selected consumption plans to each agent outside the considered subset of agents. Notice in the definition how the initial point α is also “scaled-down”. Recall that $\alpha = (\alpha_{\bar{\omega}_1} \cdot \bar{\omega}_1, \dots, \alpha_{\bar{\omega}_L} \cdot \bar{\omega}_L)$. The point $\alpha_{\bar{\omega}} \cdot \bar{\omega}_{N \setminus M}$ is,

$$\alpha_{\bar{\omega}} \cdot \bar{\omega}_{N \setminus M} = (\alpha_{\bar{\omega}_1} \cdot (\bar{\omega}_1 - x_M^1), \dots, \alpha_{\bar{\omega}_L} \cdot (\bar{\omega}_L - x_M^L)).$$

We complement *consistency* with a robustness axiom that applies to situations in which the number of agents increases, and when the feasible set is modified in an appropriate way. Thomson (1988) defines four robustness properties of rules with respect to an increase in the number agents. Among these, the one that has been the object of most of the attention in the literature is *replication invariance* that we define next.

Replication invariance: An allocation rule f_α satisfies *replication invariance* if and only if for each $(R, \bar{\omega}) \in E^N$, each $x \in f(R, \bar{\omega})$ and each $\lambda \in \mathbb{N}$,

$$\lambda x \in f_{\alpha_{\bar{\omega}} \cdot \lambda \bar{\omega}}(\lambda R, \lambda \bar{\omega}).$$

Apart from fairness and robustness, a central authority—e.g. a planner—is interested in the possibility of obtaining the allocations selected by the rule as equilibrium outcomes of some non-cooperative game—i.e. through an institution. Our point of view here is that decentralization entails full implementation of a solution. Before introducing the property of *implementability via some game-theoretic solution concept*, let us add some necessary definitions.

A game form or mechanism is a game tree with possibly simultaneous moves.⁸ More formally, it is defined as an array $\Gamma = (N, T, g)$ where N is the set of players, T a game tree, and g is an outcome function that associates a feasible allocation with each path of play. The set of nodes of the tree T is denoted S . The initial node is s_0 . The set of terminal nodes of the tree T is denoted Z . Let M_i be the set of strategies of player i , and let M_i^s denote the set of strategies available to player i at node s . Denote by $M = \prod_i M_i$, the set of strategy profiles. Suppose the strategy profile $m \in M$ is played. Let $g(m)_i$ stand for bundle obtained by agent $i \in N$ at the allocation prescribed by the path induced by m , that is, $g(m)$. Let $g(m, s)$ denotes the outcome corresponding to m starting at node s . As is common in the implementation literature, we confine our attention to pure strategies.

For the definitions at hand, suppose that the only characteristics that can vary are the preferences of agents. That is, the set of agents N and the endowment $\bar{\omega}$ are fixed. An economy then reduces to a preference profile $R \in \mathcal{R}^N$. Given an economy $R \in \mathcal{R}^N$, the mechanism Γ defines a non-cooperative game in extensive game form (Γ, R) .

Let \mathcal{SC} be a *game theoretic solution concept*. A solution concept describes a set of predictions on how a game will be played, as a function of the agents' preferences. For each $R \in \mathcal{R}^N$, the set of \mathcal{SC} -equilibrium outcomes of (Γ, R) is denoted $ESC(\Gamma, R)$.

A solution f is *implementable* in \mathcal{SC} -equilibrium if and only if for each $R \in \mathcal{R}^N$, $ESC(\Gamma, R) = f(R)$.

Examples of solutions concepts are numerous. To define just a few, a Nash equilibrium of (Γ, R) is a strategy profile $m^* \in M$ such that for each

⁸Here, we consider static as well as sequential game forms. Since a static game form can always be represented as a sequential game form with simultaneous moves, we choose this more general definition that encompasses both cases.

$i \in N$

$$g(m^*)_i R_i g(m_i, m_{-i}^*)_i \text{ for each } m_i \in M_i.$$

A subgame perfect equilibrium of (Γ, R) is a strategy profile $m^* \in M$ such that for all $s \in S \setminus Z$ and for all $i \in N$,

$$g(m^*, s)_i R_i g(m_i, m_{-i}^*, s)_i \text{ for each } m_i \in M_i.$$

But solutions concepts are not only limited to Nash equilibrium and its refinements. Solution concepts such as dominant strategies or undominated strategies are also part of our general definition.⁹

Implementability via some game-theoretic solution concept: A solution f satisfies *implementability via some game-theoretic solution concept* if and only if there exists a game theoretic solution concept \mathcal{SC} and a game form Γ such that f is implementable by Γ via \mathcal{SC} .

We close this section and give the definitions of *Maskin monotonicity* (Maskin, 1999), a necessary condition for Nash implementation and *Unchanged contour independence* (see Maniquet, 2003), a sufficient condition for subgame perfect implementation.¹⁰

Maskin monotonicity: An allocation rule f is *Maskin monotonic* if and only for each $(R, \bar{\omega}), (R', \bar{\omega}) \in E^N$, and $x \in f(R, \bar{\omega})$,

$$[LC_i(R_i, x_i) \subseteq LC_i(R'_i, x_i) \text{ for each } i \in N] \implies [x \in f(R', \bar{\omega})].$$

Unchanged contour independence: A SCC f satisfies *unchanged contour independence* if and only if for each $(R, \bar{\omega}), (R', \bar{\omega}) \in E^N$ and $x \in f(R, \bar{\omega})$,

$$[I_i(R_i, x_i) \cap A_i(\bar{\omega}) = I_i(R'_i, x_i) \cap A_i(\bar{\omega}) \text{ for each } i \in N] \implies [x \in f(R', \bar{\omega})].$$

⁹Our definition of *solution concepts* should be seen as encompassing any solution concepts commonly used in the implementation literature since they all share a common feature that will be explained in the next section: in order to break an equilibrium when going from one preference profile to another, a change in preferences is needed.

¹⁰Bochet (2005b), also shows that if non-degenerate lotteries are permitted out of equilibrium, then *Maskin monotonicity* and *Nash implementation* coincide.

3 Properties of equal-budget choice equivalent rules

In this section, we study *equal-budget choice equivalent* allocation rules. Allocation rules are indexed by a number α and can be decomposed into three categories that are specific to the region in which α is located. The first case is when¹¹,

$$\alpha \in \left\{ 0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n} \right\}$$

The second case is when¹²,

$$\alpha \in C(A(\bar{\omega})).$$

Finally, the last case is when

$$\alpha = \frac{\bar{\omega}}{n}.$$

When α is the point of equal-division, f_α is *equal-budget choice equivalent* if and only if it coincides with the *equal-income Walrasian rule*. We show this result in the lemma below.

Lemma 1 (Thomson, 1994) *Let the domain of preferences be \mathcal{R}_C^N . Consider the family of linear choice sets $\mathcal{B}_{\frac{\bar{\omega}}{n}}$. An allocation rule f_α is equal-budget choice equivalent if and only if $f_\alpha = \bar{W}_{EQ}$.*

Proof: Let f be the *equal-budget choice equivalent* allocation rule with respect to $\mathcal{B}_{\frac{\bar{\omega}}{n}}$ and let $R, \bar{\omega}$ and $x \in f(R, \bar{\omega})$ be given. By definition, there exists $p \in \Delta^{L-1}$ such that for each $i \in N$, x_i I_i x_i^* for each $x_i^* \in \arg \max R_i|_{B_{\frac{\bar{\omega}}{n}}(p)}$. Our claim is that $p \cdot x_i = p \cdot \alpha$ for each $i \in N$, i.e. $x_i \in \arg \max R_i|_{B_{\frac{\bar{\omega}}{n}}(p)}$. To see this, observe first that by definition, we have that $p \cdot x_i \geq p \cdot x_i^*$. Suppose, contrary to our claim that for some $i \in N$, $p \cdot x_i > p \cdot x_i^*$. Summing across agents, we obtain that $\sum p \cdot x_i > \sum p \cdot x_i^* = p \cdot \bar{\omega}$, a contradiction with the feasibility of x as an allocation. Therefore, $f \subset W_{EQ}$. The other inclusion is obvious.

Q.E.D.

¹¹We point out that for any $\alpha \gg \frac{\bar{\omega}}{n}$, the allocation rule f is empty at each preference profile.

¹²We voluntarily exclude the trivial corners $\{0\}$ and $\{\bar{\omega}\}$ as point of division since they both deliver empty solutions.

3.1 Robustness with Respect to Changes in Preferences and Implementation

We start this section by showing a clear connection between *independence to irrelevant preference changes* and the decentralization of a rule. In fact, such a robustness property is the most basic requirement for an allocation rule to be *implementable via some game-theoretic solution concept*. In this section, we fix the set of agents N and the endowment $\bar{\omega}$. A rule f is then a mapping $f : \mathcal{R}^N \rightarrow A(\bar{\omega})$. An economy is thus simply a preference profile R and a class of economy is simply a set of preference profiles \mathcal{R}^N .

Proposition 1: *A solution f satisfies implementability via some game-theoretic solution concept only if it satisfies independence to irrelevant preference changes.*

Proof: Since f satisfies *implementability via some game-theoretic solution concept*, there exists a solution concept \mathcal{SC} and a game form Γ such that f is implemented by Γ via \mathcal{SC} . Fix a preference profile $R \in \mathcal{R}^N$ and $x \in f(R)$. By *implementability via some game-theoretic solution concept*, there exists $m \in M$ that is an \mathcal{SC} -equilibrium such that $g(m) = x \in ESC(\Gamma, R)$.

Consider a change in preferences when going from R to R' with $R_i \cap A_i = R'_i \cap A_i$ for each $i \in N$. Thus, for some $j \in N$, $R_j \neq R'_j$ but for each $i \in N$, $R_i \cap A_i = R'_i \cap A_i$. The region where preferences determined that m was an \mathcal{SC} -equilibrium, and that $x \in ESC(\Gamma, R)$, still contains the exact same set of preferences as in R . Therefore, if m was an \mathcal{SC} -equilibrium under R , it remains one under R' . As a consequence, we have that $x \in ESC(\Gamma, R')$.

Q.E.D.

Proposition 1 states an obvious requirement for *implementability via some game theoretic solution concept*. Information on preferences outside of the feasible set cannot be used. The reason is that in order to break an equilibrium when going from one preference profile to another, a change in preferences is needed. For implementation via Nash equilibrium and any of its refinement, specific preference reversals are needed. For instance, implementation via Nash equilibrium requires that if $x \in f(R) \setminus f(R')$, there exists $i \in N$ and $y_i \in A_i$ such that $x_i R_i y_i$ and $y_i P'_i x_i$. On the other hand, for implementation via undominated strategies, if $x \in f(R) \setminus f(R')$ there exists $i \in N$ and $y_i \in A_i$ such that either $x_i R_i y_i$ and $y_i P'_i x_i$, or $x_i P_i y_i$ and $x_i I'_i$

y_i .¹³ Finally, implementation via subgame perfect equilibrium requires that if $x \in f(R) \setminus f(R')$, there exists $i \in N$, and $y_i, z_i \in A_i$ such that $y_i R_i z_i$ and $z_i P_i x_i$.

However preference changes outside of the feasible set cannot be tested since they occur at allocations that are not feasible. Therefore, an allocation rule sensitive to change in preferences outside of the feasible set can never be implemented, and this whatever solution concept used.¹⁴

Next we show that when the domain is \mathcal{R}_C^N , the only *equal-budget choice equivalent* rules that are not sensitive to a change in preferences occurring only outside of the feasible set are the rules f_α with $\alpha \in C(A(\bar{\omega}))$. Differentiability plays a crucial role in the implementation of the *equal-income Walrasian rule*. When indifference curves can have kinks, the *equal-income Walrasian rule* is not implementable via any solution concept. As expected, the problem comes from allocations that are at the boundary of the feasible set but it goes beyond the classical impossibility result on the Nash implementation of this rule.

Proposition 2: *Suppose the class of preferences is \mathcal{R}_C^N . An equal-budget choice equivalent allocation rule f_α satisfies implementability if and only if $\alpha \in C(A(\bar{\omega}))$. $\alpha \in C(A(\bar{\omega}))$.*

Proof: The proof relies on a series of lemmas.

Lemma 1: *Suppose that,*

$$\alpha \in \left\{ 0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n} \right\}.$$

The equal-budget choice equivalent allocation rule f_α with respect to \mathcal{B}_α does not satisfy implementability.

Proof: We use counter-examples to prove the claim. The examples we construct are for $\alpha = \frac{\bar{\omega}}{K}$ for $K > n$.¹⁵ The proof generalizes to any

$$\alpha \in \left\{ 0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n} \right\}.$$

¹³See Jackson (1992) for a definition of implementation in undominated strategies.

¹⁴Notice also that such allocations rules cannot be virtually implemented either. For a definition of Virtual Nash implementation, see for instance Abreu and Sen (2001) or Bochet and Maniquet (2005).

¹⁵The case $K < n$ is trivial. For any $\alpha \gg \frac{\bar{\omega}}{n}$, the equal-budget choice equivalent allocation rule with respect to \mathcal{B}_α is then empty at every preference profiles. When $\alpha > \frac{\bar{\omega}}{n}$, this is no longer true but the same type of examples we construct in the lemma can be applied.

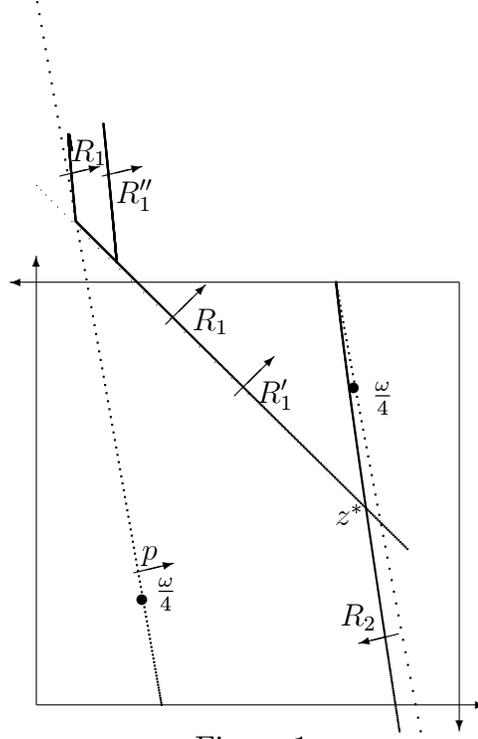


Figure 1

We consider two agents-two goods exchange economy with two possible preference profiles $R = (R_1, R_2)$ and $R' = (R'_1, R_2)$. The preferences are represented by utility functions as follows.

$$u_1(\cdot, R_1) = \min \left\{ x_1 + y_1; x_1 + \frac{1}{K+1}y_1 + \frac{5K}{K+1} \right\}$$

$$u_1(\cdot, R'_1) = x_1 + y_1$$

$$u_2(\cdot) = (K + 1)x_2 + y_2$$

The endowment is $\bar{\omega} = (4, 4)$.

For each $K > n$, when the profile is R , there exists an allocation $z^* \in f_{\frac{\bar{\omega}}{K}}(R)$, that is *equal-budget choice equivalent* and for which $(x_1, 5) \in \arg \max R_1|_{B_{\frac{\bar{\omega}}{K}}(p)} \notin A_i$, $x_1 > 0$, for some $i \in N$ and $p = (K, 1)$. The situation is depicted for the case $K = 4$ in Figure 1 above.

There is an *equal-budget choice equivalent* allocation,

$$z^* = \left(\left(\frac{123}{48}, \frac{137}{48} \right), \left(\frac{69}{48}, \frac{55}{48} \right) \right),$$

and $\arg \max R_1|_{B_{\frac{\bar{\omega}}{4}}(p)} = \left(\frac{5}{12}, 5 \right)$. However, allocation z^* is no longer *equal-budget choice equivalent* with respect to $B_{\frac{\bar{\omega}}{4}}(p)$ at R' : the indifference curve of agent 1 at the point $\left(\frac{5}{12}, 5 \right)$ extends below $B_{\frac{\bar{\omega}}{4}}(p)$ and hence $\left(\frac{5}{12}, 5 \right) \notin \arg \max R'_1|_{B_{\frac{\bar{\omega}}{4}}(p)} = \left(0, \frac{20}{3} \right)$. Finally, observe that the preferences of agents

inside the feasible set have not changed. The correspondence $f_{\frac{\bar{\omega}}{4}}$ is not implementable in **any** game theoretical solution concept. It is clear that the same conclusion applies to any $K > n$.

The counter-examples we used were based on an extension of an indifference curve below the set $B_{\frac{\bar{\omega}}{K}}(p)$ for agent 1 when going from R to R' . For each $K > n$, the same conclusion remains true even if there is an expansion of the lower contour set at z^* outside of the feasible set. To see this, suppose that there is also a third preference profile (R_1'', R_2) at which preferences of agent 1 are given by $u_1(\cdot, R_1'') = \min \left\{ x_1 + y_1; x_1 + \frac{1}{K+1}y_1 + \frac{4.5K}{K+1} \right\}$. As seen in Figure 1, there is an expansion of the lower contour set for agent 1 when going from R to R'' but the expansion occurs outside of the feasible set while the preferences inside the feasible set remain unchanged. This shows that the violation of *implementability* is not restricted to \mathcal{R}_C^N but **also** applies to \mathcal{R}_D^N as well.

Finally, notice that the examples we have used are based on extension of budget sets beyond the upper boundary of the Edgeworth box. For a point $\alpha = (0, k)$ with $k < \bar{\omega}^2$, the extension of the budget sets will occur on the right boundary of the box. The same examples as we have constructed above can be adapted to this case.

Q.E.D.

Lemma 2: *Suppose the class of preferences is \mathcal{R}_C^N . The allocation rule W_{EQ} does not satisfy implementability*

Proof: We adapt the counter example of lemma 1 to the case $K = n = 2$. The aggregate endowment is $\bar{\omega} = (4, 4)$. The preferences of agents are as follows.

$$u_1(\cdot, R_1) = \min \left\{ x_1 + y_1; x_1 + \frac{1}{3}y_1 + \frac{8}{3} \right\} \text{ and } u_1(\cdot, R_1') = x_1 + y_1.$$

$$u_2(\cdot) = 2x_2 + y_2$$

When the profile is R , there exists an equal-income Walrasian equilibrium (z^*, p^*) on the boundary of the feasible set with $z^* = ((1, 4); (3, 0))$ and $p^* = (2, 1)$.

The situation is depicted graphically in Figure 2 on the next page.

Allocation z^* is no longer an equal-income Walrasian equilibrium under R' . However, there exists no agent i and no pair $x_i, y_i \in A_i$ such that

$$x_i R_i y_i \text{ and } y_i P_i' x_i.$$

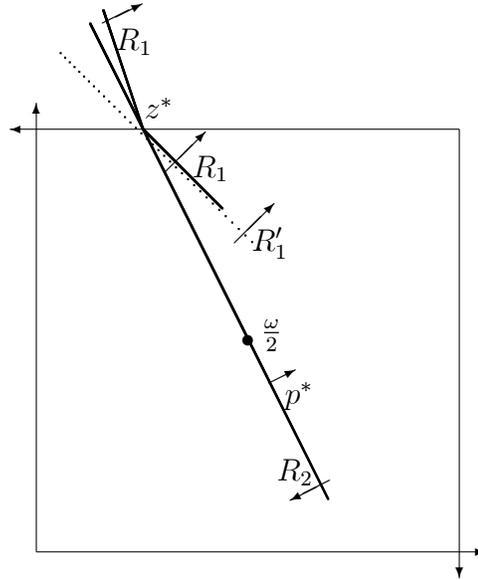


Figure 2

In conclusion, the *equal-income Walrasian rule* is not implementable in **any** solution concept.¹⁶

Q.E.D.

Lemma 3: *Suppose that $\alpha \in C(A(\bar{\omega}))$, then f_α satisfies implementability.*

Proof: Clearly, f_α satisfies *independence to irrelevant preference changes*. To see this, observe that whenever the common budget set extends outside of the feasible set, then indifference curves of agents never intersect. That is, whenever given $p \in \Delta^{L-1}$, the common budget set extends outside of the feasible set, we have that $\cap_{i \in N} \{x_i \in B_\alpha(p)\} \neq \emptyset$.

Though necessary, this condition is far from being sufficient. In fact, it is enough to observe that for any such α , f_α satisfies *unchanged contour independence*, a sufficient condition for subgame perfect implementation.¹⁷ Given $R \in \mathcal{R}_C^N$, for each $x \in f_\alpha(R)$, there exists $p \in \Delta^{L-1}$ such that $\cap_{i \in N} \{x_i \in B_\alpha(p)\} = \emptyset$, and for each $i \in N$, $x_i \in \arg \max R_i|_{B_\alpha(p)} \in A_i$. Consider a profile $R' \in \mathcal{R}_C^N$ such that $I_i(R_i, x_i) \cap A_i = I_i(R'_i, x_i) \cap A_i$ for each $i \in N$. We have that for each $i \in N$, $z_i \in \arg \max R_i|_{B_\alpha(p)} \iff$

¹⁶Obviously, the same is true for any initial distribution of the aggregate endowment different of equal-division: if the domain is \mathcal{R}^{ND} , then the *Walrasian correspondence* is not implementable in any solution concept (see Bochet, 2005a).

¹⁷Observe that if $\alpha \in C(A(\bar{\omega}))$, f_α is not *Maskin monotonic* and hence not Nash implementable.

$z_i \arg \max R'_i|_{B_\alpha(p)}$. Therefore, $x \in f(R')$.

Q.E.D.

The combination of lemma 1 to 3 completes the proof of Proposition 2.

Proposition 3: *Suppose the class of preferences is \mathcal{R}_D^N . An equal-budget choice equivalent allocation rule f_α satisfies implementability if and only if $\alpha \in C(A(\bar{\omega})) \cup \{\frac{\bar{\omega}}{n}\}$.*

Proof: We have already shown in lemma 1 that even if preferences are differentiable and $\alpha \in \{0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n}\}$, then f_α cannot satisfy *equal-budget choice equivalence* and *implementability*.

Finally, observe that W_{EQ} now satisfies *unchanged contour independence* (see Maniquet (2003) and Bochet (2005a)).¹⁸

Q.E.D.

Remark 1: Only a few allocation rules satisfy *equal-budget choice equivalence* and *implementability*. By the first welfare theorem, W_{EQ} only contains *Pareto efficient* allocations. This is clearly not the case when $\alpha \neq \frac{\bar{\omega}}{n}$. We point out in passing that whenever $\alpha \neq \frac{\bar{\omega}}{n}$, there does not exist a *Pareto efficient* and Nash implementable selection of the *equal-budget choice equivalent* allocation rule f_α .

Moreover, our point of view is that the boundary rules do not offer a sensible approach to fairness. After all, when deciding how to first divide the resources, the preferences of agents are in general unknown to the planner. By discarding some goods, the planner goes against a principle of neutrality with respect to goods. For instance suppose that there are two goods, food and water. The planner should not decide to give water to agents but no food to start with when both items are available. It implies that the name of the goods should not matter. This is the familiar *neutrality* axiom defined below.

Neutrality: An allocation rule f_α satisfies *neutrality* if and only if for each permutation $\pi : L \rightarrow L$ and each $R \in \mathcal{R}^N$,

$$x \in f_\alpha(R) \implies \pi \circ x \in f_{\pi \circ \alpha}(\pi \circ R).$$

Based on this argument, a strengthening of proposition 3 with neutrality would provide a simple “characterization” of the equal-income Walrasian

¹⁸Obviously, the *equal-income Walrasian allocation rule* is not implementable in dominant strategies, in undominated strategies or in Nash equilibrium.

rule. In addition, it provides a further justification of equal-division of resources as a first step towards fairness.

3.2 Robustness with Respect to Change in the Number of Agents

In this section we go back to the initial setting introduced in section 2, where the number of agents in the economy can vary. We start with the study of our second robustness property, *consistency*.¹⁹

Proposition 4: *Suppose the class of economies is E_D^N . An allocation rule f_α satisfies consistency if and only if $\alpha = \frac{\bar{w}}{n}$.*

Proof:

First part: The fact that W_{EQ} satisfies consistency is well-known (see Thomson, 1988). We recall its proof for the sake of completeness.

Take an economy $(R, \bar{w}) \in E_D^N$ and fix $x \in W_{EQ}(R, \bar{w})$. By definition, there exists $p \in \Delta^{L-1}$ such that for each $i \in N$, $x_i \in \arg \max R_i|_{B_{\frac{\bar{w}}{n}}(p)}$. Given the assumptions on preferences, for each $i \in N$, $p \cdot x_i = p \cdot \frac{\bar{w}}{n}$. Consider a subeconomy $M \subset N$. The total resources available in this subeconomy after the departure of agents in $N \setminus M$ with their respective bundle is $\sum_{i \in M} x_i$. Hence, allocation x_M is still feasible. Since $p \cdot x_i = p \cdot \frac{\bar{w}}{n}$, we have that $p \cdot \frac{\sum_{j \in M} x_j}{|M|} = p \cdot \frac{\bar{w}}{n}$. Therefore, $B_{\frac{\bar{w}}{n}}(p) = B_{\frac{\sum_{j \in M} x_j}{|M|}}(p)$ and thus $x_j \in f_{\frac{\sum_{j \in M} x_j}{|M|}}(R \setminus R_{N \setminus M}, \sum_{j \in M} x_j)$.

Second part: To see that when α is one of the corners of the Edgeworth cube, *consistency* may be violated, let us look at the following example.

There are three agents and two goods, $\bar{w} = (4, 2)$. At profile $R \in \mathcal{R}_D^N$, agents 1 and 2 have utility functions given by $u_i(x_i, y_i) = \frac{2}{3}x_i + y_i$ and $u_3(x_3, y_3) = 3x_3 + y_3$. Consider $\alpha = (0, \bar{w}_y)$ and the allocation $z = ((1.5, 1); (1.5, 1); (1, 0))$. This allocation is *equal-opportunity equivalent*. Given $p = (2, 1)$, $\arg \max R_i|_{B_\alpha(p)} = (0, 2)$ for $i = 1, 2$, $\arg \max R_3|_{B_\alpha(p)} = (1, 0)$ and $\arg \max R_j|_{B_\alpha(p)} I_i z_j$ for each $j = 1, 2, 3$. Suppose that agent 1 leaves the economy with z_1 . By *consistency*, $((1.5, 1); (1, 0)) \in f_{(0,1)}(R \setminus R_1, (2.5, 1))$.

¹⁹Thomson (1988) showed that if indifference curves have kinks, then W_{EQ} does not satisfy consistency. Hence, for the remainder of the paper, the class of economies we consider is E_D^N .

The only price vector such that $\arg \max R_3|_{B_{(0,1)}(p)} = (1, 0)$ is $p = (1, 1)$. At this prices, $\arg \max R_2|_{B_{(0,1)}(p)} = (0, 1)$ but $z_2 P_i \arg \max R_2|_{B_{(0,1)}(p)}$, a contradiction with the fact that f_α satisfies *equal-budget choice equivalence*.

Third part: Next, we show that when $\alpha \notin C(A(\bar{\omega})) \cup \{\frac{\bar{\omega}}{n}\}$, *consistency* is also violated. We use one counter-example but it should be clear that the same can be shown for any other $\alpha \notin C(A(\bar{\omega})) \cup \{\frac{\bar{\omega}}{n}\}$.

Again we consider a three agents-two goods example with $\bar{\omega} = (5, 2)$ and $\alpha = (0.5, 2)$. At profile $R \in \mathcal{R}_D^N$, agents $i = 1, 2$ have utility functions given by $u_i = x_i + y_i$ and $u_3 = (x_3)^2 y_3$. Allocation $z = ((2, 0.5); (2, 0.5); (1, 1))$ is *equal-opportunity equivalent* with respect to \mathcal{B}_α for $p = (2, 1)$. Suppose now that agent 1 leaves with z_1 . The reduced economy has $\bar{\omega} = (3, 1.5)$ and $\alpha = (0.3, 1.5)$. By consistency, $((2, 0.5); (1, 1)) \in f_{(0.3, 1.5)}(R \setminus R_1, (3, 1.5))$. The only price vector such that $\arg \max R_2|_{B_{(0.3, 1.5)}(p)} I_2(2, 0.5)$ is $p = (\frac{15}{22}, 1)$. However, $\arg \max R_3|_{B_{(0.3, 1.5)}(\frac{15}{22}, 1)} P_3 z_3$, a contradiction with *equal-budget choice equivalence*.

We conclude that the proposition holds if and only if $\alpha = \frac{\bar{\omega}}{n}$.

Q.E.D.

We conclude our results by the study of *replication invariance*. We provide a characterization that parallels a result that appears in Thomson (1988). He shows that a selection from the *Pareto efficient* and *equal-split lower bound* correspondence satisfies *consistency* and *replication invariance* if and only if it is a subrule of the *equal-income Walrasian rule*.

Proposition 5: *Suppose the class of preferences is \mathcal{R}_D^N and fix $\alpha \in \mathbb{R}_+^L$. Any Pareto efficient selection from f_α satisfies consistency and replication invariance if and only if $\alpha = \frac{\bar{\omega}}{n}$.*

Proof: Let $\alpha = \alpha_{\bar{\omega}} \cdot \bar{\omega} \in \mathbb{R}_+^L$, $(R, \bar{\omega}) \in E_D^N$ and $x \in f_{\alpha_{\bar{\omega}} \cdot \bar{\omega}}(R, \bar{\omega})$ be given. By *Pareto efficiency*, there exists $p \in \Delta^{L-1}$ that supports x . Suppose that $x \notin W_{EQ}(R, \bar{\omega})$. Then there exists $i \in N$ with $p \cdot x_i > p \cdot \frac{\bar{\omega}}{n}$ and $j \in N$ with $p \cdot x_j < p \cdot \frac{\bar{\omega}}{n}$. By convexity and monotonicity of preferences, there exists $\lambda_i, \lambda_j \in \mathbb{N}$ and y such that $y P_j x_j$, and

$$y = \frac{\lambda_i x_i + \lambda_j x_j}{\lambda_i + \lambda_j}.$$

Define $\lambda \equiv \max \{\lambda_i, \lambda_j\}$. By *replication invariance*, $\lambda x \in f_{\alpha_{\bar{\omega}} \cdot \lambda \bar{\omega}}(\lambda R, \lambda \bar{\omega})$. Consider a subeconomy of λR composed of λ_i agents of type i and λ_j agents of

type j . By *consistency*, we obtain that $(\lambda x_i, \lambda x_j) \in f_{\alpha_{\bar{\omega}}(\lambda_i + \lambda_j)\lambda y}(\lambda_i R_i, \lambda_j R_j, \lambda(\lambda_i + \lambda_j)y)$. By *equal-opportunity equivalence*, there exists $p \in \Delta^{L-1}$ such that $\lambda x_k \ I_k \ \arg \max R_k|_{B_{\lambda y}(p)} R_k \ \alpha_{\bar{\omega}}(\lambda_i + \lambda_j)\lambda y$ for $k = i, j$. This implies that $\lambda x_j \ R_j \ \alpha_{\bar{\omega}}(\lambda_i + \lambda_j)\lambda y$, and $\alpha_{\bar{\omega}}(\lambda_i + \lambda_j)\lambda x_j \ P_j \ \alpha_{\bar{\omega}}(\lambda_i + \lambda_j)\lambda y$, a contradiction with the initial assumption that $y \ P_j \ x_j$.

Q.E.D.

We conclude the paper with two remarks.

Remark 2: As seen in lemma 2, for some preference domains, the *equal-income Walrasian correspondence* is not implementable via any game-theoretical solution concept. On the other hand, a correspondence called the *constrained equal-income Walrasian correspondence*, CW_{EQ} , is Nash implementable. Given the deficits of the allocation rules we have studied, one can alternatively look at a constrained version of *equal-budget choice equivalence*.

Given $\alpha \in \{0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n}\}$ and $p \in \Delta^{L-1}$, a constrained linear choice set is $\bar{B}_\alpha(p) \equiv \{x \in A_i(\bar{\omega}) : p \cdot x \leq p \cdot \alpha\}$. Based on this definition, we can reformulate our axiom in term of *constrained equal-opportunity equivalence* and *constrained equal-budget choice equivalence*.

Constrained equal-opportunity equivalence: An allocation $x \in A(\bar{\omega})$ is *constrained equal-opportunity equivalent relative to the family \mathcal{B}_α* for $R \in \mathcal{R}^N$ if there exists $\bar{B}_\alpha(p) \in \mathcal{B}_\alpha$ such that for each $i \in N$, $x_i \ I_i \ x_i^*$ for some $x_i^* \in \arg \max R_i|_{\bar{B}_\alpha(p)}$.

The definition of *equal-budget choice equivalence* allocation rule \bar{f}_α then just follows. When $\alpha \in \{0 < \alpha' < \bar{\omega} : \alpha' \notin C(A(\bar{\omega})) \text{ and } \alpha' \neq \frac{\bar{\omega}}{n}\}$, every \bar{f}_α is subgame perfect implementable. However, notice that the only Nash implementable allocation rule is the *constrained equal-income Walrasian rule* CW_{EQ} .²⁰ Therefore, an allocation rule \bar{f}_α satisfies *constrained equal-budget choice equivalence* and *Maskin monotonicity* if and only if $\bar{f}_\alpha = CW_{EQ}$.²¹ Observe that $WE_{EQ} \subseteq CW_{EQ}$. In addition, if preferences are strongly monotonic, then for any $(R, \bar{\omega}) \in E^N$ and any $x \in CW_{EQ}(R, \bar{\omega})$, allocation x is *Pareto efficient*. An important observation is that if $\alpha \neq \frac{\bar{\omega}}{n}$, then \bar{f}_α is

²⁰Thomson (1999) in fact shows that CW_{EQ} is the minimal Maskin monotonic extension of WE_{EQ} .

²¹Observe that a selection of the Constrained equal-income Walrasian rule is not necessarily Maskin monotonic.

neither a subcorrespondence nor a supercorrespondence of its unconstrained counterpart f_α .

Remark 3: An interesting extension would be to consider fair solutions suggested in the literature and to construct the family of choice sets generating them as *equal-opportunity equivalent* solutions. If they satisfy *implementation via some game theoretic solution concept*, then the components of the family of choice sets (e.g. bundles, allocations etc...) can be used as part of the strategy sets of agents. For instance, suppose that a given solution is Nash implementable using a family of choice sets \mathcal{B} . Then, we conjecture that the announcements of preference profiles in canonical mechanisms such as Abreu and Sen (1990) for subgame perfect implementation; Maskin (1999) or Bochet (2005b) for Nash implementation; can be replaced by announcements of choice sets. This work would suggest a close connection between *equal-opportunity equivalence* and the possibility to perform strategy space reductions from infinite to finite spaces in canonical mechanisms used to \mathcal{SC} -implement an allocation rule.

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